

# ECU-4x8

## SUBSEA CONTROLLER

Used to control electric & hydraulic ROV's, manipulators, hydraulic valve packages, tool systems & for subsea & industrial applications.

Communicates to surface remote control station over RS485 twisted pair for 2,500ft (0.75km) maximum range. Can interface to fiber optic link for 6 mile (10km) range.

All system functions can be controlled with surface laptop PC running Sub F/X control software. Redundant control using optional surface control unit with panel mounted switches, joysticks, potentiometers, LED's, etc.

System using single main board can control 8 switch closure outputs, 8 digital inputs, 8 analog outputs (0 to +5V or -5 to +5V), 6 analog inputs (0-5V) & 2 4-wire bridge inputs (0-100mV).

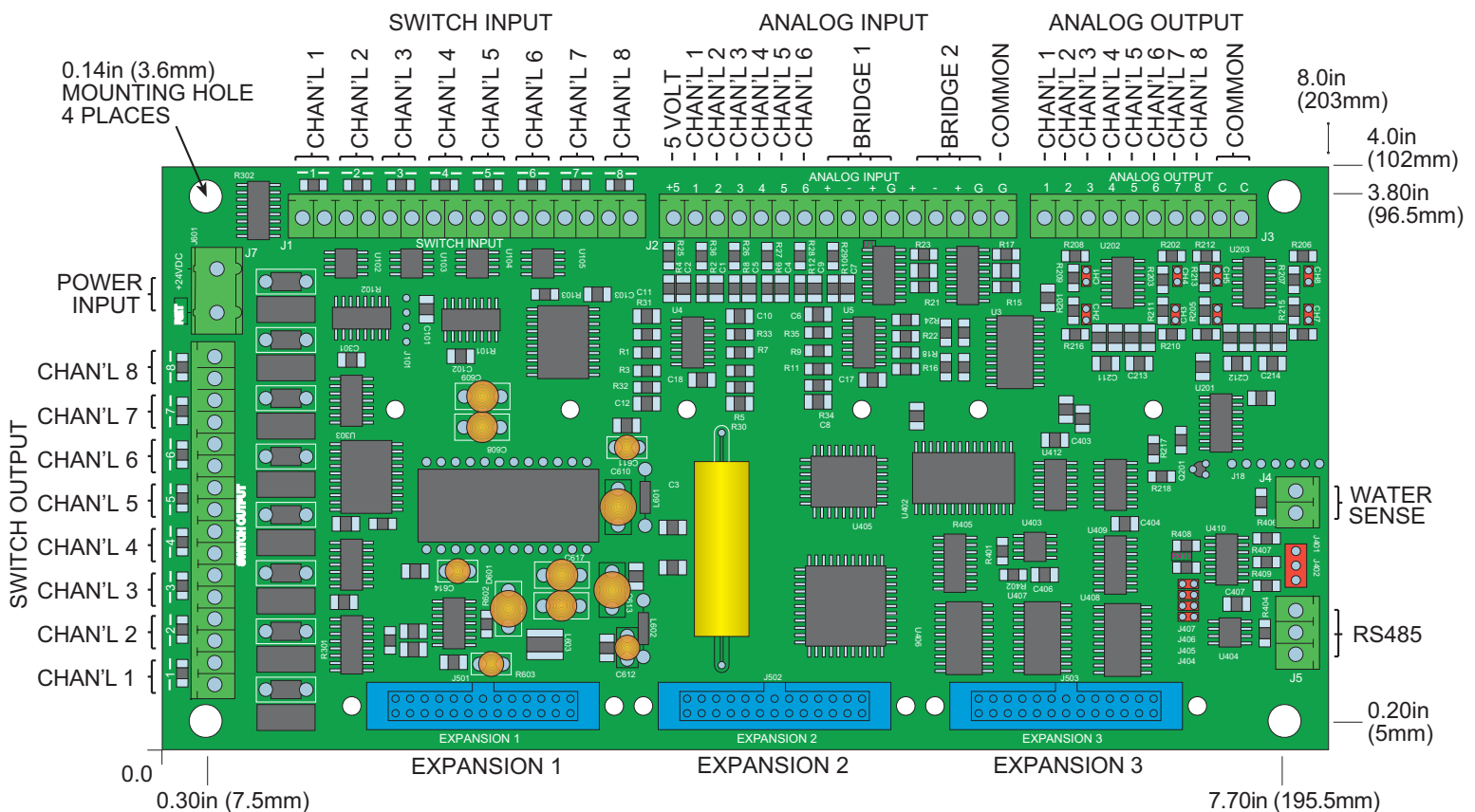
System using single main board and plug-in expansion cards can have up to 32 switch closure outputs, 32 digital inputs, 8 PWM outputs (0 to 100% @ 10A each) & 8 quadrature encoder inputs.

Other expansion cards include an RS232 card with 4 3-wire ports, a 2-channel servo card & a surface controller card.

Up to 16 main boards can be "daisy chained" for control & monitoring of very large systems.

Sub F/X control software operates in Windows 98 & NT & provides a fully customized graphical user interface.

Main board and expansion cards feature pressure tolerant electronics rated to 8,500psi (580 bar).



### Specifications

#### Dimensions:

Main Board: 8.0in (203mm) long x 4.0in (102mm) wide x 1.0in (25mm) high w/o expansion cards.  
Expansion cards increase height to 2.0in (50mm).

#### Power Requirements:

12 - 24 VDC, 1 amp.

Total current, including load current, not to exceed 50A.

#### Main Board Contains:

8 High Current open drain diode protected outputs capable of switching up to 10 amps each.

8 Switch contact closure inputs.

16 LED indicators to display any active digital input.

8 8-bit analog outputs (0 to +5 volt or -5 to +5 volt, individually jumper selectable) 5mA.

6 12-bit analog inputs (0 to +5 volt).

2 12-bit analog inputs (0 to 100mV) 4 wire bridge.

1 Water sensor alarm input.

RS485 half duplex communication port.

2 TTL 3-wire serial ports (RS232).

3 Expansion slots (see Expansion Boards).

Board identification jumper selectable (1 of 16) for multiple cards on bus.

Sub F/X software runs on Windows 98 & NT, and provides a fully customizable graphical user interface with on-screen switches & LEDs, compass rosette & bar & digital displays.

Sub F/X software also includes power mixing for joysticks, trend graphs, sensor calibration, if-then-else programming & more.

#### Expansion Boards

4 different expansion boards can be plugged into any of the 3 available expansion slots on the main board. Any combination of expansion boards can be used (3 maximum) including:

*PWM-8* - (8) High Current open drain diode protected PWM outputs capable of controlling up to 10 amps from 0 to 100%.

*DIO-8* - (8) High Current open drain diode protected outputs capable of switching up to 10 amps with indicator LED's.

*DIN-8* - (8) Switch contact closure inputs.

*SERVO-2* - (2) Closed loop velocity servos with high current PWM and 0 to 5v DC output (8-bit), jumper selectable. Feedback input up to 5v DC. Servo supports programmable feedback and loop gain stored in EPROM on card.

*ENC-8* - (8) 16-bit TTL level quadrature encoder inputs.

*SCU-1* - Converts ECU card to surface control with 32 LED outputs, 32 switch inputs.

*SERIAL 4* - (4) 2-wire RS232 ports, 2400-115k baud.